## K. J. Somaiya Institute of Technology, Sion, Mumbai-22 (Autonomous College Affiliated to University of Mumbai)

Nov - Dec 2024

(B. Tech ) Program: EXTC Scheme I/II/IIB/III:

Regular Examination: SY Semester: VII

Course Code: EXDLC7043

and

Course Name: Robotics

Date of Exam: 23/11/2024 Duration: 02.5 Hours

Max. Marks: 60

## Instructions:

(1)All questions are compulsory.

(2)Draw neat diagrams wherever applicable.

(3) Assume suitable data, if necessary.

Q. No.	Question	Max. Marks	СО	BT level
Q 1	Solve any two questions out of three: (05 marks each)	10		
a)	Define Following  1) Accuracy 2) Precision 3) repeatability		1	U
b)	Find a Composite Rotation Matrix for robots if its Mobile coordinate frame is rotated by angle 30 degree about f1, 60 degree about f2 and 30 degree about f3.		4	Ap
c)	What are heading sensors? Explain utility of this sensor in Mobile Robotics		3	U
Q 2	Solve any two questions out of three: (05 marks each)	10	12	
a)	Explain on off controller in the operation of controlling speed of motor.	no.in	2	U
b)	Explain challenges in localization of Sensor aliasing and effector noise.	n herry	5	U
c)	Write a short note on Architecture for behavior-based Navigation		6	U
Q. 3	Solve any two questions out of three: (10 marks each)			
a)	Find out expression for $_{\mathcal{C}}^{\mathcal{B}}T$	20		Ap

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	<b>↑</b> {D}		4	
	(A) (C) (B)			
p)	Define Following  1) Homogeneous Transformation Matrix and 2) Inverse Homogeneous Transformation matrix 3) Accuracy and	en ma vocal anni: andre: a anni:	1	U
	Precision 5  Explain BLDC motor control techniques.		2	U
c)	Solve any two questions out of three: (10 marks each)	20	No.	
Q.4		nec Do	3	U
a)	Explain PID controller and write a Pseudo code for PID controller.		5	U
	Compare Bug-1 and Bug-2 algorithm.		6	U
b)	Describe Subsumption architecture of level 2 with example.		6	