

K. J. Somaiya Institute of Technology, Sion, Mumbai-22
(Autonomous College Affiliated to University of Mumbai)

~~May-June 2025~~
July/Aug 2025

Supplementary

Program: B. Tech. Scheme IIB

KT Examination Semester: IV

Course Code: EXC405 and Course Name: Signals and Systems

Date of Exam: ~~28/05/2025~~

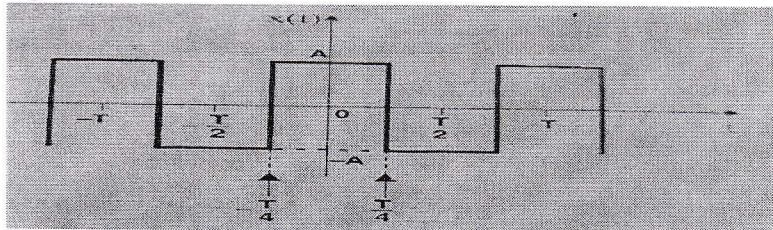
Duration: 02.5 Hours

Max. Marks: 60

06/08/2025

Instructions:

- (1) All questions are compulsory.
- (2) Draw neat diagrams wherever applicable.
- (3) Assume suitable data, if necessary.

Q. No.	Question	Max. Marks	CO	BT level
Q 1	Solve any two questions out of three: (05 marks each)	10		
a)	State whether following signals $x(t)$ is periodic or not? if periodic, find fundamental period of following signals : $x(t) = 2 \cos(100\pi t) + 3 \sin(50t)$		1	Ap
b)	Compute Autocorrelation function of : $x(t) = e^{-8t} u(t)$		2	Ap
c)	Determine Trigonometric Fourier series coefficient a_n of the following signal: 		3	Ap
Q 2	Solve any two questions out of three: (05 marks each)	10		
a)	Find Fourier transform of following time functions and sketch their magnitude spectrum of $x(t) = e^{-at} u(t)$; $a > 0$.		4	Ap
b)	Determine Initial and final value for following signal using Laplace transform: $X(s) = (s+5)/[s^2(s+9)]$		5	Ap
c)	Determine z Transform and ROC in Z plane of following sequences: $x(n) = n(1/4)^n u(n)$		6	Ap

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Q.3	Solve any two questions out of three. (10 marks each)	20		
a)	Determine cross-correlation for the sequence $x_1(n) = [1, 2, 3, 4]$ and $x_2(n) = [3, 2, 1, 0]$ by using direct computation and tabular method.		1	Ap
b)	Obtain Convolution of given signals using Convolution Integral with neat sketches. $x(t) = 1; -1 \leq t \leq 1$ and $h(t) = 1; 0 \leq t \leq 2$		2	Ap
c)	Consider a causal LTI system with $H(j\omega) = 1/(j\omega + 2)$. For particular input $x(t)$, this system produces output $y(t) = e^{-2t} u(t) - e^{-3t} u(t)$, Compute $x(t)$ using Fourier Transform.		4	Ap
Q.4	Solve any two questions out of three. (10 marks each)	20		
a)	Determine whether the system described by i) $y(t) = tx(t)$ ii) $y(n) = x(-n)$ is static/dynamic, linear/nonlinear, time-variant/time invariant, causal/noncausal, stable/unstable.		2	Ap
b)	The differential equation of the system is $(d^2y(t)/dt^2) + 3(dy(t)/dt) + 2y(t) = x(t)$ with zero initial conditions input $x(t) = e^{-3t} u(t)$. Using Laplace Transform determines output of the system.		5	Ap
c)	Determine Inverse z Transform of $X(z) = 1/(1 - 0.8z^{-1} + 0.12z^{-2})$ i) ROC : $ z > 0.6$ ii) ROC : $ z < 0.2$ iii) ROC : $0.2 < z < 0.6$ by using partial fraction method.		6	Ap
