## University of Mumbai

## Examination 2020 under cluster 5 (Lead College: APSIT)

Examinations Commencing from 23 $^{\text {rd }}$ December 2020 to $6^{\text {th }}$ January 2021 and from $7^{\text {th }}$ January 2021 to 20 ${ }^{\text {th }}$ January 2021
Program: Bachelor of Engineering
Curriculum Scheme: Electronics \& Telecommunication (Rev2019 "C")
Examination: SE Semester III
Course Code: ECC305 and Course Name: Electronic Instrumentation \& Control Systems
Time: 2 Hour
Max. Marks: 80

| Q1. | Choose the correct option for following questions. All the Questions are compulsory and carry equal marks |
| :---: | :---: |
|  |  |
| 1. | On which principle Wheatstone bridge works? |
| Option A: | full deflection |
| Option B: | partial deflection |
| Option C: | null deflection |
| Option D: | no diffraction |
|  |  |
| 2. | The simplest type of bridge used for the measurement of medium inductance is a - |
| Option A: | Maxwell |
| Option B: | Schering |
| Option C: | Hey |
| Option D: | Wheatstone |
|  |  |
| 3. | The principle of Homogeneity and superposition is applied to --- |
| Option A: | Linear time-variant system |
| Option B: | Non-linear time-variant system |
| Option C: | Linear time-invariant system |
| Option D: | Non-linear time-invariant system |
|  |  |
| 4. | In Force-Voltage analogy, damper is analogous to - - - |
| Option A: | Inductance |
| Option B: | Charge |
| Option C: | Current |
| Option D: | Resistance |
|  |  |
| 5. | A Schering bridge can be used for the ---- |
| Option A: | protecting the circuit from temperature rises |
| Option B: | testing capacitors |
| Option C: | measuring voltages |
| Option D: | measuring currents |
|  |  |
| 6. | The overall transfer function, from block diagram reduction, for parallel blocks is |
| Option A: | Sum of individual gain |


| Option B: | Difference of individual gain |
| :---: | :---: |
| Option C: | Product of individual gain |
| Option D: | Division of individual gain |
| 7. | The steady state error due to a step input $A u(t)$ is given by --- |
| Option A: | $A /(1+K p)$ |
| Option B: | $A / K p$ |
| Option C: | 1/AKp |
| Option D: | $K p /(1+A)$ |
| 8. | What is the Type and the Order of the system, $G(s)=\frac{100(s+5)(s+30)}{s^{3}(s+2)\left(s^{2}+3 s+10\right)}$. |
| Option A: | 4 and 9 |
| Option B: | 4 and 7 |
| Option C: | 3 and 5 |
| Option D: | 3 and 6 |
| 9. | Which among the following second order systems will take more time to reach it's steady state value? |
| Option A: | Undamped system |
| Option B: | Critically damped system |
| Option C: | Overdamped system |
| Option D: | Underdamped system |
| 10. | The characteristic equation of a system is given below. Find the range of values for k . $\mathrm{s}^{3}+3 \mathrm{ks}^{2}+(\mathrm{k}+2) \mathrm{s}+4=0$ |
| Option A: | $0<\mathrm{k}<0.523$ |
| Option B: | $0.527<\mathrm{k}<$ infinity |
| Option C: | $0.678<\mathrm{k}<$ infinity |
| Option D: | $0.21<\mathrm{k}<0.527$ |
| 11. | Function of transducer is to convert --- - |
| Option A: | Electrical signal into non electrical quantity |
| Option B: | Electrical signal into mechanical quantity |
| Option C: | Non electrical quantity into electrical signal |
| Option D: | To do nothing |
| 12. | The change in loading and unloading curves is known as ---- |
| Option A: | Zero drift characteristics |
| Option B: | Sensitivity drift |
| Option C: | Hysteresis |
| Option D: | Zero drift plus sensitivity drift characteristics |


| 13 | Phase margin of the system is used to specif |
| :---: | :---: |
| Option A: | relative stability |
| Option B: | absolute stability |
| Option C: | time response |
| Option D: | frequency response |
| 14. | If damping ratio of a given system is 0.5 , then the lines joining complex poles with origin are inclined to negative real axis at ---- |
| Option A: | $\pm 90 \mathrm{deg}$ |
| Option B: | $\pm 60 \mathrm{deg}$ |
| Option C: | $\pm 45 \mathrm{deg}$ |
| Option D: | $\pm 30 \mathrm{deg}$ |
| 15. | In Bode diagram, the factor $1 /(j w)(j w)$ in the transfer function gives a line having slope |
| Option A: | 20 dB per decade |
| Option B: | 40 dB per decade |
| Option C: | -20 dB per decade |
| Option D: | -40 dB per decade |
| 16. | Where are the closed loop poles of the following system located? $G(s) H(s)=\frac{1}{s^{2}+49}$ |
| Option A: | They are located on negative real axis |
| Option B: | They are located on $j w$ axis |
| Option C: | They are located on right half of s-plane |
| Option D: | They are located, one on the right half and one on the left half |
| 17. | The open loop transfer function of a unity feedback system is given by $G(s)=\frac{K(s+2)}{s\left(s^{2}+2 s+2\right)}$. The centroid is ---- |
| Option A: | 0 |
| Option B: | -1/2 |
| Option C: | -2/3 |
| Option D: | 1/2 |
| 18. | Gain margin is the reciprocal of the gain at the frequency at which the phase angle is ---- |
| Option A: | 90 deg |
| Option B: | 180 deg |
| Option C: | -180 deg |
| Option D: | 0 deg |
| 19. | A system has 8 poles and 3 zeros. The slope of its highest frequency asymptote in its magnitude plot is ---- |
| Option A: | $-40 \mathrm{~dB} /$ decade |
| Option B: | $-60 \mathrm{~dB} /$ decade |
| Option C: | -100 dB/decade |
| Option D: | $-150 \mathrm{~dB} /$ decade |


|  |  |
| :---: | :--- |
| 20. | Settling time is inversely proportional to product of the damping ratio and $-\cdots$ |
| Option A: | Time constant |
| Option B: | Maximum overshoot |
| Option C: | Peak time |
| Option D: | Undamped natural frequency |


| Q2. | Answer the following : |
| :---: | :--- |
| A | Solve any Two |
| i. | Explain functional blocks of a measurement system. |
| ii. | Compare temperature transducers RTD and Thermocouple. <br> iii. <br> having forward path transfer function as <br> $G(s)=\frac{36}{s(s+8)}$. |
| B | Solve any One for a unity feedback system |
| i. | Obtain transfer function of the block diagram shown in figure - marks each <br> ii. |


| Q3. | Answer the following : |
| :---: | :--- |
| A | Solve any Two |
| i. | Explain the working principle of LVDT with a neat sketch. 5 marks each |
| ii. | What are compensators? Why are they needed in control systems? |
| ii. | Sketch polar plot of <br> $G(s)=\frac{1}{s(s+a)(s+b)}$. <br> B <br> i. <br> Solve any One <br> ii. <br> Draw Bode plot for a unity feedback control system with open loop transfer <br> function, <br> $G(s)=\frac{K}{s(1+s)(1+0.1 s)}$. <br> Investigate the $s t a b i l i t y ~ o f ~ t h e ~ s y s t e m ~ t h a t ~ h a s ~ t h e ~ c h a r a c t e r i s t i c ~ e q u a t i o n ~: ~$ <br> $s^{5}+2 s^{4}+24 \mathrm{~s}^{3}+48 \mathrm{~s}^{2}-25 \mathrm{~s}-50=0$ |

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Max. Marks: 80

| Question <br> Number | Correct Option (Enter either ' $A$ ' or ' $B$ ' or 'C' or 'D') |
| :---: | :---: |
| Q1. | C |
| Q2. | A |
| Q3. | C |
| Q4 | D |
| Q5 | B |
| Q6 | A |
| Q7 | A |
| Q8. | D |
| Q9. | C |
| Q10. | B |
| Q11. | C |
| Q12. | C |
| Q13. | A |
| Q14. | B |
| Q15. | D |
| Q16. | B |
| Q17. | A |
| Q18. | C |
| Q19. | C |
| Q20. | D |

